Index to volume 1 (1991)

Articles

January (pp 1 – 56)

Soft-sensors for process estimation and inferential control
M. T. Tham, G. A. Montague, A. J. Morris and P. A. Lant 3–14
Comparison of single loop and QDMC-based control of crude oil distillation towers
L. Hsie and T. J. McAvoy 15–21
Modelling of a fixed-bed water-gas shift reactor 1. Steady-state model verification
N. H. Bell and T. F. Edgar 22–31
Order reduction of non-linear differential algebraic process models
H.-P. Löffler and W. Marquardt 32–40
Design of adaptive controllers for non-linear stirred tank bioreactors: extension to the MIMO situation
D. Dochain 41–48
Robust control of oscillations in isothermal continuous stirred tank aerosol reactors
M. Chidambaram and Y. S. N. Malleswararao 49–54

March (pp 57–120)

Modelling of a fixed-bed water-gas shift reactor 2. Variable catalyst activity effects and dynamic testing
N. H. Bell and T. F. Edgar 59–67
Benefits from process control: results of a joint industry–university study
T. E. Marlin, J. D. Perkins, G. W. Barton and M. L. Brisk 68–83
Adaptive control: theory and practical aspects
K. Najim and M. M'Saad 84–95
On-line estimation and control of a continuous stirred tank polymerization reactor
K. J. Kim and K. Y. Choi 96–110
Human problems with computer control in process plants
T. A. Kletz 111–115

May (pp 121–176)

Critique of exact linearization strategies for process control
M. A. Henson and D. E. Seborg 122–139
Multivariable control experiments of non-linear chemical processes using non-linear feedback transformation
K. Nakamoto and N. Watanabe 140–145
Robust control of a batch-fed fermenter
J. Bhat, M. Chidambaram and K. P. Madhavan 146–151
Dissolved oxygen control through an adaptive non-linear model approach: a simulation study
J. R. Pérez-Correa, F. López and I. Solar 152–160
Interaction between process design and process control: the role of open-loop indicators
G. W. Barton, W. K. Chan and J. D. Perkins 161–170
Robust control of a distillation column by the method of inequalities
E. S. Prabhu and M. Chidambaram 171–176

August (pp 171–240)

Calculation of steady-state gains for multivariable systems from closed-loop steady-state data
A. R. McIntosh and V. Mahalec 178–186
A robust/cautious model predictive controller
K. P. Fruzzetti, A. Palazoglu, J. A. Romagnoli and K. A. McDonald 187–196
Advanced control of a sugar crystallizer
D. I. Wilson, P. L. Lee, E. T. White and R. B. Newell 197–206
Application of predictive control techniques to a distillation column
D. G. Lewis, C. L. Evans and D. J. Sandoz 207–216
Model-based control of a blast furnace stove rig
G. A. Labossiere and P. L. Lee 217–227
Adaptive process control using pattern-based performance feedback
R. F. Hinde Jr. and D. J. Cooper 228–238

November (pp 241–296)

Interaction between process design and process control: economic analysis of process dynamics
L. T. Narraway, J. D. Perkins and G. W. Barton 243–250
Improved state estimator in the face of unreliable parameters
M. Agarwal and D. Bonvin 251–257
Process fault diagnosis with diagnostic rules based on structural decomposition
J. Zhang and P. D. Roberts 259–269
An adaptive controller for batch feed bioprocess application to lycine production
J. M. Flaus, A. Cheruy and J. M. Engasser 271–281
Further developments in output structural controllability and an assessment of structural techniques
X. Lin and R. B. Newell 283–292

Keywords

Adaptive control
Batch feed
Lysine 271–281
Bioreactors
Non-linear dynamics 41–48
Mathematical models
Parameter estimation 84–95
Model reference control
Pattern recognition 228–238
Non-linear algorithms
Models 152–160
Batch feed
Lysine
Adaptive control 271–281
Batch processing
Crystallization
Kalman filter 197–206
Batch-fed reactor
Fermenter
Non-linear control 146–151
Bioreactors
Non-linear dynamics

Adaptive control 41–48
Blast furnace stove
Generic model control (GMC)
PID controller 217–227
Case studies
Control benefits
Upgrading 68–83
Catalyst activity
Non-linear dynamics
Mathematical modelling 59–67
Closed loops
Steady-state gains
Multivariable systems 178–186
Condition number
Singular value analysis
Controllability 161–170
Control
Feedback control
Oscillation 49–54
Model
Crude towers 15–21
Non-linear dynamics 22–31
Structural controllability
Synthesis 283–292
Control benefits
Upgrading
Case studies 68–83
Controllability
Condition number
Singular value analysis 161–170
Crude towers
Control
Model 15–21
Crystallization
Kalman filter
Batch processing 197–206
Decoupling
Linearization
Non-linear process 140–145
Diagnostic rules
Fault diagnosis
Expert systems 259–269
Distillation column
Sampled data models
Predictive control 207–216
Reflux flow
Method of inequalities 171–176
Dynamics
Model
Non-linear 32–40
Economic performance
Modelling
Process design 243–250
Errors
Simulation
State estimation 251–257
Estimation
Feedback control
Sensors 3–14
Exact linearization strategies
Input-output linearization 122–139
Expert systems
Diagnostic rules
Fault diagnosis 259–269
Fault diagnosis
Expert systems
Diagnostic rules 259–269
Feedback control
Oscillation
Control 49–54
Sensors
Estimation 3–14
Fermenter
Non-linear control
Batch-fed reactor 146–151
Generic model control (GMC)
PID controller
Blast furnace stove 217–227
Input-output linearization
Exact linearization strategies
122–139
Kalman filter
Batch processing
Crystallization 197–206
Linearization
Non-linear process
Decoupling 140–145
Lysine
Adaptive control
Batch feed 271–281
Mathematical modelling
Catalyst activity
Non-linear dynamics 59–67
Parameter estimation
Adaptive control 84–95
Method of inequalities
Distillation columns
Reflux flow 171–176
Model
Crude towers
Control 15–21
Non-linear
Dynamics 32–40
Non-linear dynamics
Control 22–31
Predictive control
Robustness 187–196
Reactor
Polymerization 96–110
Model reference control
Pattern recognition
Adaptive control 228–238
Modelling
Process design
Economic performance 243–250
Models
Adaptive control
Non-linear algorithms 152–160
Multivariable systems
Closed loops
Steady-state gains 178–186
Non-linear
Dynamics
Model 32–40
Non-linear algorithms
Models
Adaptive control 152–160
Non-linear control
Batch-fed reactor
Fermenter 146–151
Non-linear dynamics
Adaptive control
Bioreactors 41–48
Control
Model 22–31
Mathematical modelling
Catalyst activity 59–67
Non-linear process
Decoupling
Linearization 140–145
Oscillation
Control
Feedback control 49–54
Parameter estimation
Adaptive control
Mathematical models 84–95
Pattern recognition
Adaptive control
Model reference control 228–238
PID controller
Blast furnace stove
Generic model control (GMC) 217–227
Polymerization
Model
Reactor 96–110
Predictive control
Distillation column
Sampled data models 207–216
Robustness
Model 187–196
Process design
Economic performance
Modelling 243–250
Reactor
Polymerization
Model 96–110
Reflux flow
Method of inequalities
Distillation columns 171–176
Robustness
Model
Predictive control 187–196
Sampled data models
Predictive control
Distillation column 207–216
Sensors
Estimation
Feedback control 3–14
Simulation
State estimation
Errors 251–257
Singular value analysis
Controllability
Condition number 161–170
State estimation
Errors
Simulation 251–257
Steady-state gains
Multivariable systems
Closed loops 178–186
Structural controllability
Synthesis
Control 283–292
Synthesis
Control
Structural controllability 283–292
Upgrading
Case studies
Control benefits 68–83

Authors

Agarwal, M. 251–257
Barton, G. W. 68–83, 161–170, 243–250
Bell, N. H. 22–31, 59–67
Bhat, J. 146–151
Bonvin, D. 251–257
Brisk, M. L. 68–83
Chan, W. K. 161–170
Cheruy, A. 271–281
Chidambaram, M. 49–54, 146–151, 171–176
Choi, K. Y 96–110

Cooper, D. J. 228–238
Dochain, D. 41–48
Edgar, T. F. 22–31, 59–67
Engasser, J. M. 271–281
Evans, C. L. 207–216
Flaus, J. M. 271–281
Fruzzetti, K. P. 187–196
Henson, M. A. 122–139
Hinde Jr., R. F. 228–238
Hsie, L. 15–21
Kim, K. J. 96–110
Kletz, T. A. 111–115
Labossiere, G. A. 217–227
Lant, P. A. 3–14
Lee, P. L. 197–206, 217–227
Lewis, D. G. 207–216
Lin, X. 283–292
Löffler, H.-P. 32–40
López, F. 152–160
Madhavan, K. P. 146–151
Mahalec, V. 178–186
Malleswarara, Y. S. N. 49–54
Marlin, T. E. 68–83
Marquardt, W. 32–40
McAvoy, T. J. 15–21
McDonald, K. A. 187–196
McIntosh, A. R. 178–186
Montague, G. A. 3–14
Morris, A. J. 3–14
M'Saad, M. 84–95
Najim, K. 84–95
Nakamoto, K. 140–145
Narraway, L. T. 243–250
Newell, R. B. 197–206, 283–292
Palazoglu, A. 187–196
Pérez-Correa, J. R. 152–160
Perkins, J. D. 68–83, 161–170, 243–250
Prabhu, E. S. 171–176
Roberts, P. D. 259–269
Ramagnoli, J. A. 187–196
Sandoz, D. J. 207–216
Seborg, D. E. 122–139
Solar, I. 152–160
Tham, M. T. 3–14
Watanabe, N. 140–145
White, E. T. 197–206
Wilson, D. I. 197–206
Zhang, J. 259–269

Book reviews

Control Systems Engineering by S. P. Banks
C. McGreavy 239
Modern Control Systems by J. A. Borrie
C. McGreavy 117
Multivariable Feedback Design by J. M. Maciejowski
J. Perkins 55